# An Efficient Algorithm for Solving Coupled Lane-Emden Boundary Value Problems in Catalytic Diffusion Reactions: The Homotopy Analysis Method 

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#### Abstract

In this paper, we use the homotopy analysis method (HAM) with Green's function [1] for solving the coupled Lane-Emden boundary value problems which appear in catalytic diffusion reactions. Due to the presence of singularity, these problems pose difficulties in obtaining their solutions. To overcome the singular behavior at the origin, the coupled Lane-Emden boundary value problems are transformed into an equivalent Fredholm integral equations. The integral forms of the Lane-Emden equations are then solved by the HAM. Unlike, Adomian decomposition method (ADM), the HAM contains an adjustable parameters to control the convergence of solution. For speed up the calculations, the discrete averaged residual error is used to obtain optimal value of the adjustable parameter $c_{0}$ to control the convergence of solution. The numerical results show that the HAM gives reliable algorithm for analytic approximate solutions of these systems. The error analysis of the sequence of the analytic approximate solutions has been performed by computing the residual error functions and the maximal residual error parameters, which demonstrate an approximate exponential rate of convergence.


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## 1 Introduction

The astrophysicists Jonathan Homer Lane and Robert Emden studied the Lane-Emden equations, where they considered the thermal behavior of a spherical cloud of gas acting under the mutual attraction of its molecules and subject to the classical laws of thermodynamics [2]. The Lane-Emden equation has been used to model several phenomena in mathematical physics and astrophysics such as the theory of stellar structure, the thermal behavior of a spherical cloud of gas, isothermal gas spheres and the theory of thermionic currents [3]. This equation also describes the temperature or concentration variation in many fields of physics, chemistry, biology, biochemistry, and many others such as isothermal and non-isothermal reaction diffusion process inside a porus cylindrical or spherical catalysts [3], solidification of cylindrical and spherical objects [4] and thermal explosion in rectangular slab [5]. A substantial amount of work has been done on these types of problems for various structures [6-23] and the references cited therein. The singular behavior that occurs at $x=0$ gives the main difficulty for solving the Lane-Emden equations.

Systems of Lane-Emden equations arise in the modelling of several physical and chemical phenomena, such as pattern formation, population evolution, chemical reactions, and so on [24-28]. In [26, 27], the Adomian decomposition method was used to solve the Volterra integral form of the Lane-Emden equation with initial values and boundary conditions.

We consider the coupled of Lane-Emden boundary value problems:

$$
\left\{\begin{array}{l}
w_{i}^{\prime \prime}(x)+\frac{k_{i}}{x} w_{i}^{\prime}(x)+f_{i}\left(w_{1}(x), w_{2}(x)\right)=0, \quad k_{i} \geq 1 \quad i=1,2 \quad x \in(0,1)  \tag{1.1}\\
w_{i}^{\prime}(0)=0, \quad w_{i}(1)=c_{i},
\end{array}\right.
$$

where $c_{i}$ are real constants.

In this work we extend the HAM combined with the Green's function strategy [1] to solve the coupled Lane-Emden boundary value problems in catalytic diffusion reactions of the form (1.1). We will show that using the integral form facilitates the computational work and overcomes the singularity behavior at $x=0$. The error analysis will be performed by using the residual error functions and the maximal error residual parameters, which demonstrate an approximate exponential rate of convergence.

## 2 The HAM for integral form of Lane-Emden equations

To convert the coupled of Lane-Emden boundary (1.1) into integral equation, it is written in the following form

$$
\begin{equation*}
\left(x^{k_{i}} w_{i}^{\prime}(x)\right)^{\prime}=x^{k_{i}} f_{i}\left(w_{1}(x), w_{2}(x)\right), \quad i=1,2 \tag{2.1}
\end{equation*}
$$

Equation (2.1) is integrated twice first from 0 to $x$ and then from $x$ to 1 , then by changing the order of integration, and applying the boundary conditions $w_{i}^{\prime}(0)=0, w_{i}(1)=c_{i}, \quad i=$ 1,2 , we obtain for $k_{i}=1$ as

$$
w_{i}(x)=c_{i}+\int_{0}^{x} \ln x s^{k_{i}} f_{i}\left(w_{1}(s), w_{2}(s)\right) d s+\int_{x}^{1} \ln s s^{k_{i}} f_{i}\left(w_{1}(s), w_{2}(s)\right) d s, \quad i=1,2
$$

and for $k_{i} \neq 1$, we have

$$
w_{i}(x)=c_{i}+\int_{0}^{x} \frac{x^{1-k_{i}}-1}{1-k_{i}} s^{k_{i}} f_{i}\left(w_{1}(s), w_{2}(s)\right) d s+\int_{x}^{1} \frac{s^{1-k_{i}}-1}{1-k_{i}} s^{k_{i}} f_{i}\left(w_{1}(s), w_{2}(s)\right) d s, \quad i=1,2 .
$$

The equivalent the Fredholm integral form of Lane-Emden equation (1.1) (for details see [18]) is given by

$$
\begin{equation*}
w_{i}(x)=c_{i}+\int_{0}^{1} K_{i}(x, s) s^{k_{i}} f_{i}\left(w_{1}, w_{2}\right) d s, \quad i=1,2 \tag{2.2}
\end{equation*}
$$

where $K_{i}(x, s)$ are given below. For $k_{i}=1, i=1,2$

$$
K_{i}(x, s)= \begin{cases}\ln s, & x \leq s  \tag{2.3}\\ \ln x, & s \leq x\end{cases}
$$

and for $k_{i}>1, i=1,2$

$$
K_{i}(x, s)= \begin{cases}\frac{s^{1-k_{i}}-1}{1-k_{i}}, & x \leq s  \tag{2.4}\\ \frac{x^{1-k_{i}}-1}{1-k_{i}}, & s \leq x\end{cases}
$$

As stated earlier, we will apply in this work the HAM combined with the Green's function
strategy [1]. The HAM was developed and improved by S. Liao [29-34] for solving a wide class of functional equations. Various modifications of HAM have been also elaborated, for example, the optimal homotopy asymptotic method (OHAM) was proposed by Marinca and Herisanu [35-38], the optimal homotopy analysis method was proposed in [39-41], and the spectral homotopy analysis method [42]. Other works based on HAM can be found in [1, 43].

According to the HAM, the zero-order deformation equation may be written as

$$
\begin{equation*}
(1-q)\left[\phi_{i}(x, q)-w_{i 0}\right]=q c_{i 0} N_{i}\left[\phi_{i}(x, q)\right], \quad i=1,2, \tag{2.5}
\end{equation*}
$$

where $q \in[0,1]$ is an embedding parameter, $w_{i 0}$ are initial guesses, $c_{i 0} \neq 0$ are convergence control parameters, $\phi_{i}(x, q)$ are unknown functions and $N_{i}\left[\phi_{i}(x, q)\right]$ are defined as

$$
\begin{equation*}
N_{i}\left[\phi_{i}(x, q)\right]=\phi_{i}(x, q)-c_{i}-\int_{0}^{1} K_{i}(x, s) s^{k_{i}} f_{i}\left(\phi_{1}(s, q), \phi_{2}(s, q)\right) d s=0, \quad i=1,2 . \tag{2.6}
\end{equation*}
$$

At $q=0$, (2.5) reduces to $\phi_{i}(x, 0)=w_{i, 0}$ and at $q=1$, it leads to $N_{i}\left[\phi_{i}(x, 1)\right]=0$ which is exactly the same as (2.2) provided that $\phi_{i}(x, 1)=w_{i}(x)$. Thus, as $q$ increasing form 0 to $1, \phi_{i}(x, q)$ moves from $w_{i 0}$ to $w_{i}$.

We expand $\phi_{i}(x, q)$ in a Taylor series with respect to $q$ to get

$$
\begin{equation*}
\phi_{i}(x, q)=w_{i 0}(x)+\sum_{m=1}^{\infty} w_{i m}(x) q^{m}, \quad i=1,2, \tag{2.7}
\end{equation*}
$$

where

$$
\begin{equation*}
w_{i m}(x)=\left.\frac{1}{m!} \frac{\partial^{m} \phi_{i}(x, q)}{\partial q^{m}}\right|_{q=0}, \quad i=1,2 . \tag{2.8}
\end{equation*}
$$

If the convergence parameter $c_{0} \neq 0$ is chosen properly, the series (2.7) converges for $q=1$ and it becomes

$$
\begin{equation*}
\phi_{i}(x, 1) \equiv w_{i}(x)=w_{i 0}(x)+\sum_{m=1}^{\infty} w_{i m}(x), \quad i=1,2, \tag{2.9}
\end{equation*}
$$

which will be the solutions of the problem (2.2).

We now define the vector

$$
\vec{w}_{i m}=\left\{w_{i 0}(x), w_{i 1}(x), \ldots, w_{i m}(x)\right\}, \quad i=1,2
$$

Differentiating (2.5) $m$-times with respect to $q$, dividing them by $m$ !, setting subsequently $q=0$, the $m$ th-order deformation equations are obtained

$$
\begin{equation*}
w_{i m}(x)-\chi_{m} w_{i(m-1)}(x)=c_{i 0} R_{i m}\left(\vec{w}_{i(m-1)}, x\right), \quad i=1,2 \tag{2.10}
\end{equation*}
$$

where $\chi_{m}$ is given by

$$
\chi_{m}= \begin{cases}0, & m \leq 1  \tag{2.11}\\ 1, & m>1\end{cases}
$$

and

$$
\begin{align*}
R_{i m}\left(\vec{w}_{i(m-1)}, x\right) & =\left.\frac{1}{(m-1)!} \frac{\partial^{m-1}}{\partial q^{m-1}} N_{i}\left[\phi_{i}(x, q)\right]\right|_{q=0}=\left.\frac{1}{(m-1)!} \frac{\partial^{m-1}}{\partial q^{m-1}} N_{i}\left(\sum_{k=0}^{\infty} w_{i k} q^{k}\right)\right|_{q=0} \\
& =w_{i(m-1)}(x)-\left(1-\chi_{m}\right) c_{i}-\int_{0}^{1} K_{i}(x, s) s^{k_{i}} H_{i(m-1)} d s, \quad i=1,2 \tag{2.12}
\end{align*}
$$

where $H_{i m}$ are given by

$$
\begin{equation*}
H_{i(m)}=\left.\frac{1}{(m)!} \frac{\partial^{m}}{\partial q^{m}} f\left(\sum_{k=0}^{\infty} w_{1 k} q^{k}, \sum_{k=0}^{\infty} w_{2 k} q^{k}\right)\right|_{q=0}, \quad i=1,2 . \tag{2.13}
\end{equation*}
$$

Using (2.10) and (2.12), the $m$ th-order deformation equations are simplified as

$$
\begin{equation*}
w_{i m}-\chi_{m} w_{i(m-1)}=c_{i 0}\left(w_{i(m-1)}-\left(1-\chi_{m}\right) c_{i}-\int_{0}^{1} K_{i}(x, s) s^{k_{i}} H_{i(m-1)} d s\right), i=1,2 . \tag{2.14}
\end{equation*}
$$

Taking $w_{i 0}=c_{i}, i=1,2$, the solution components will be computed as:

$$
\left\{\begin{array}{l}
w_{i 1}(x)=c_{i 0}\left(w_{i 0}(x)-c_{i 0}-\int_{0}^{1} K_{i}(x, s) s^{k_{i}} H_{i 0} d s\right)  \tag{2.15}\\
w_{i 2}(x)=\left(1+c_{i 0}\right) w_{i 1}(x)-c_{i 0} \int_{0}^{1} K_{i}(x, s) s^{k_{i}} H_{i 1} d s \\
\vdots \\
w_{i m}(x)=\left(1+c_{i 0}\right) w_{i(m-1)}(x)-c_{i 0} \int_{0}^{1} K_{i}(x, s) s^{k_{i}} H_{i(m-1)} d s, \quad m=3,4, \ldots
\end{array}\right.
$$

The $M$ th-order approximate solutions of the problem (2.2) are given by

$$
\begin{equation*}
\phi_{i M}\left(x, c_{i 0}\right)=\sum_{m=0}^{M} w_{i m}\left(x, c_{i 0}\right), \quad i=1,2 . \tag{2.16}
\end{equation*}
$$

To select the appropriate convergence control parameters $c_{i 0}$ has a big influence on the convergence region of series (2.16) and on the convergence rate as well [41, 44]. One of the methods for selecting the value of convergence control parameter is the so-called $c_{i 0}$-curve and the horizontal line may be considered as the valid interval for $c_{i 0}[31,45]$. This method enables to determine the effective region of the convergence control parameter, however it does not give the possibility to determine the value ensuring the fastest convergence [41]. Another way to find the optimal value of the convergence-control parameters $c_{i 0}$ is obtained by minimizing the squared residual of governing equation

$$
\begin{equation*}
\Delta_{i M}\left(c_{i 0}\right)=\int_{0}^{1}\left[N_{i}\left(\phi_{i M}\left(x, c_{i 0}\right)\right)\right]^{2} d x, \quad i=1,2 . \tag{2.17}
\end{equation*}
$$

However, the exact squared residual error $\Delta_{i M}\left(c_{i 0}\right)$ is expensive to calculate when $M$ is large. For speed up the calculations Liao [40, 41] suggested to replace the integral in formula (2.17) by its approximate value obtained by applying the quadrature rules. So, we approximate $\Delta_{i M}\left(c_{i 0}\right)$ by the so-called discrete averaged residual error defined by

$$
\begin{equation*}
\Delta_{i M}\left(c_{i 0}\right)=\frac{1}{n} \sum_{j=1}^{n}\left[N_{i}\left(\phi_{i M}\left(x_{j}, c_{i 0}\right)\right)\right]^{2}, \quad i=1,2 \tag{2.18}
\end{equation*}
$$

where $x_{j}=j h, h=x_{j}-x_{j-1}$. The optimal values $c_{i 0}$ will be obtained by solving

$$
\begin{equation*}
\frac{\partial \Delta_{i M}}{\partial c_{i 0}}=0, \quad i=1,2 \tag{2.19}
\end{equation*}
$$

and then those values will be substituted in (2.16) to get the optimal approximate solutions.

## 3 The HAM for BVP in catalytic diffusion reactions

Consider the particular case of the coupled Lane-Emden equations (1.1) with the quadratic and product nonlinearities as [25]:

$$
\left\{\begin{array}{l}
w_{1}^{\prime \prime}(x)+\frac{2}{x} w_{1}^{\prime}(x)-k_{11} w_{1}^{2}(x)-k_{12} w_{1}(x) w_{2}(x)=0  \tag{3.1}\\
w_{2}^{\prime \prime}(x)+\frac{2}{x} w_{2}^{\prime}(x)-k_{21} w_{1}^{2}(x)-k_{22} w_{1}(x) w_{2}(x)=0
\end{array}\right.
$$

with boundary conditions

$$
\begin{cases}w_{1}^{\prime}(0)=0, & w_{1}(1)=c_{1}  \tag{3.2}\\ w_{2}^{\prime}(0)=0, & w_{2}(1)=c_{2}\end{cases}
$$

The coupled Lane-Emden equations (3.1) and (3.2) occurs in catalytic diffusion reactions [25]. The parameters $c_{1}, c_{2}, k_{11}, k_{12}, k_{21}$ and $k_{22}$ can be specified for the actual chemical reactions. In [25] authors studied the qualitative analysis for the solutions. In [26], Adomian decomposition method was applied to solve (3.1) and (3.2) by fixing parameters $c_{1}=1, c_{2}=2, k_{11}=k_{22}=1, k_{12}=2 / 5, k_{21}=1 / 2$. All of the computations have been performed using the MATHEMATICA software.

According to the HAM with Green's function (2.14), we have the following iteration formulation for (3.1) and (3.2) as

$$
\left\{\begin{array}{l}
w_{1 m}-\chi_{m} w_{1(m-1)}=c_{10}\left[w_{1(m-1)}-\left(1-\chi_{m}\right) c_{1}-\int_{0}^{1} K_{1}(x, s) s^{2} H_{1(m-1)} d s\right]  \tag{3.3}\\
w_{2 m}-\chi_{m} w_{2(m-1)}=c_{20}\left[w_{2(m-1)}-\left(1-\chi_{m}\right) c_{2}-\int_{0}^{1} K_{2}(x, s) s^{2} H_{2(m-1)} d s\right]
\end{array}\right.
$$

where $K_{i}(x, s)$ are given below. For $k_{i}=2, i=1,2$

$$
K_{i}(x, s)= \begin{cases}\frac{s^{1-k_{i}}-1}{1-k_{i}}, & x \leq s  \tag{3.4}\\ \frac{x^{1-k_{i}}-1}{1-k_{i}}, & s \leq x\end{cases}
$$

### 3.1 For $c_{1}=1, c_{2}=2, k_{11}=k_{22}=1, k_{12}=2 / 5, k_{21}=1 / 2$

Using (3.3) with $w_{10}=c_{1}, w_{20}=c_{2}$, and fixing the parameters $c_{1}=1, c_{2}=2, k_{11}=$ $1, k_{12}=2 / 5, k_{21}=1 / 2$ and $k_{22}=1$, the 4th-order approximations are obtained as

$$
\begin{align*}
\phi_{14}= & 1+\frac{9 c_{10}}{10}+\frac{597 c_{10}^{2}}{500}+\frac{55973 c_{10}^{3}}{105000}+\frac{7 c_{10} c_{20}}{120}+\frac{1613 c_{10}^{2} c_{20}}{47250}+\frac{65 c_{10} c_{20}^{2}}{3024}-\left(\frac{9 c_{10}}{10}\right. \\
& \left.+\frac{33 c_{10}^{2}}{25}+\frac{9611 c_{10}^{3}}{15000}+\frac{c_{10} c_{20}}{12}+\frac{1409 c_{10}^{2} c_{20}}{27000}+\frac{67 c_{10} c_{20}^{2}}{2160}\right) x^{2}+\left(\frac{63 c_{10}^{2}}{500}+\frac{563 c_{10}^{3}}{5000}\right. \\
& \left.+\frac{c_{10} c_{20}}{40}+\frac{91 c_{10}^{2} c_{20}}{4500}+\frac{7 c_{10} c_{20}^{2}}{720}\right) x^{4}-\left(\frac{173 c_{10}^{3}}{35000}+\frac{137 c_{10}^{2} c_{20}}{63000}+\frac{c_{10} c_{20}^{2}}{5040}\right) x^{6} .  \tag{3.5}\\
\phi_{24}= & 2+\frac{5 c_{20}}{4}+\frac{63 c_{10} c_{20}}{200}+\frac{1961 c_{10}^{2} c_{20}}{14000}+\frac{67 c_{20}^{2}}{48}+\frac{673 c_{10} c_{20}^{2}}{5040}+\frac{3139 c_{20}^{3}}{6048}-\left(\frac{5 c_{20}}{4}\right. \\
& \left.+\frac{9 c_{10} c_{20}}{20}+\frac{413 c_{10}^{2} c_{20}}{2000}+\frac{35 c_{20}^{2}}{24}+\frac{713 c_{10} c_{20}^{2}}{3600}+\frac{487 c_{20}^{3}}{864}\right) x^{2}+\left(\frac{27 c_{10} c_{20}}{200}+\frac{141 c_{10}^{2} c_{20}}{2000}\right. \\
& \left.+\frac{c_{20}^{2}}{16}+\frac{83 c_{10} c_{20}^{2}}{1200}+\frac{13 c_{20}^{3}}{288}\right) x^{4}+\left(-\frac{57 c_{10}^{2} c_{20}}{14000}-\frac{13 c_{10} c_{20}^{2}}{2800}-\frac{c_{20}^{3}}{2016}\right) x^{6} . \tag{3.6}
\end{align*}
$$

Applying (2.18) and (2.19), we obtain optimal values $c_{10}=-0.767463, c_{20}=-0.789762$ and hence the HAM approximations to the solutions are obtained as

$$
\begin{align*}
& \phi_{14}(x)=0.780767+0.191485 x^{2}+0.0244069 x^{4}+0.00334088 x^{6} .  \tag{3.7}\\
& \phi_{24}(x)=1.68960+0.273372 x^{2}+0.0326694 x^{4}+0.00436072 x^{6} \tag{3.8}
\end{align*}
$$

and by setting $c_{10}=c_{20}=-1$, the ADM approximations to the solutions are obtained as

$$
\begin{align*}
& \psi_{14}(x)=0.763625+0.220604 x^{2}+0.00845556 x^{4}+0.00731587 x^{6}  \tag{3.9}\\
& \psi_{24}(x)=1.66822+0.30988 x^{2}+0.0126944 x^{4}+0.00921032 x^{6} \tag{3.10}
\end{align*}
$$

To examine the accuracy and applicability of the HAM, we define the residual and max-



Figure 1 Plots of the HAM $\phi_{14}(x)$ and ADM Figure 2 Plots of the HAM $\phi_{24}(x)$ and ADM $\psi_{14}(x)$ solutions $\psi_{24}(x)$ solutions
imum absolute residual errors as

$$
\begin{align*}
\operatorname{Res}_{i M}(x) & =\left|\phi_{i M}^{\prime \prime}+\frac{2}{x} \phi_{i M}^{\prime}-k_{11} \phi_{1 M}^{2}-k_{12} \phi_{1 M}^{2} \phi_{2 M}^{2}\right|, \quad i=1,2  \tag{3.11}\\
R_{i M} & =\max _{0 \leq x \leq 1} \operatorname{Res}_{i M}(x), \quad i=1,2  \tag{3.12}\\
\operatorname{res}_{i M}(x) & =\left|\psi_{i M}^{\prime \prime}+\frac{2}{x} \psi_{i M}^{\prime}-k_{11} \psi_{1 M}^{2}-k_{12} \psi_{1 M}^{2} \psi_{2 M}^{2}\right|, \quad i=1,2  \tag{3.13}\\
r_{i M} & =\max _{0 \leq x \leq 1} \operatorname{res}_{i M}(x), \quad i=1,2, \tag{3.14}
\end{align*}
$$

where $\phi_{i M}$ are $\psi_{i M}$, the HAM solutions and are the ADM solutions, respectively.
The numerical results of approximate solutions ( $\phi_{i 4}, \psi_{i 4}, i=1,2$ ), the absolute residual errors $\left(\operatorname{Res}_{i 4}(x), \operatorname{res}_{i 4}(x), i=1,2\right)$, and the maximum absolute residual errors ( $R_{i 4}, r_{i 4}, i=1,2$ ) obtained by the HAM and the ADM are given in Tables 1-3 for $c_{1}=1, c_{2}=2, k_{11}=k_{22}=1, k_{12}=2 / 5, k_{21}=1 / 2$ and in Tables 4-6 for $c_{1}=1, c_{2}=$ $2, k_{11}=k_{12}=k_{21}=k_{22}=1$.

Table 1 The HAM and ADM approximations to solutions

| $x$ | $\phi_{14}$ | $\psi_{14}$ | $\phi_{24}$ | $\psi_{24}$ |
| :--- | :---: | :---: | :---: | :---: |
| 0.0 | 0.780767047 | 0.763624868 | 1.689598095 | 1.668215608 |
| 0.1 | 0.782684342 | 0.765831758 | 1.692335084 | 1.671315683 |
| 0.2 | 0.788465717 | 0.772463013 | 1.700585517 | 1.680631694 |
| 0.3 | 0.798200840 | 0.783553024 | 1.714469358 | 1.696214314 |
| 0.4 | 0.812043169 | 0.799167888 | 1.734191780 | 1.718159052 |
| 0.5 | 0.830215964 | 0.819418576 | 1.760051017 | 1.746622830 |
| 0.6 | 0.853020705 | 0.844479370 | 1.792449348 | 1.781847192 |
| 0.7 | 0.880847918 | 0.874611567 | 1.831907230 | 1.824188148 |
| 0.8 | 0.914190405 | 0.910192446 | 1.879080563 | 1.874152645 |
| 0.9 | 0.953658877 | 0.951749513 | 1.934781102 | 1.932441674 |
| 1.0 | 1.000000000 | 1.000000000 | 2.000000000 | 2.000000000 |

Table 2 The absolute residual errors

| $x$ | $\operatorname{Res}_{14}(x)$ | res $_{14}(x)$ | $\operatorname{Res}_{24}(x)$ | $\operatorname{res}_{24}(x)$ |
| :--- | :---: | :---: | :---: | :---: |
| 0.0 | 0.011640586 | 0.230942914 | 0.016249657 | 0.766598470 |
| 0.1 | 0.011385744 | 0.226867128 | 0.015921395 | 0.763378418 |
| 0.2 | 0.010641294 | 0.214888858 | 0.014966847 | 0.754062831 |
| 0.3 | 0.009458900 | 0.195746198 | 0.013466018 | 0.739676243 |
| 0.4 | 0.007895555 | 0.170637696 | 0.011515827 | 0.721894603 |
| 0.5 | 0.005967766 | 0.141171286 | 0.009172894 | 0.702994203 |
| 0.6 | 0.003582957 | 0.109285297 | 0.006368090 | 0.685772693 |
| 0.7 | 0.000443210 | 0.077133580 | 0.002786970 | 0.673434203 |
| 0.8 | 0.004085554 | 0.046923639 | 0.002292183 | 0.669427479 |
| 0.9 | 0.011148438 | 0.020692579 | 0.010214085 | 0.677221825 |
| 1.0 | 0.022633272 | $8.41341 \mathrm{E}-17$ | 0.023231283 | 0.700000000 |

Table 3 The maximum absolute residual errors

| $M$ | $R_{1 M}$ | $r_{1 M}$ | $R_{2 M}$ | $r_{2 M}$ |
| :--- | :---: | :---: | :---: | :---: |
| 2 | $4.665 \mathrm{E}-01$ | $8.666 \mathrm{E}-01$ | $5.998 \mathrm{E}-01$ | 1.56667 |
| 3 | $9.750 \mathrm{E}-02$ | $4.428 \mathrm{E}-01$ | $6.772 \mathrm{E}-02$ | $7.100 \mathrm{E}-01$ |
| 4 | $1.164 \mathrm{E}-02$ | $2.309 \mathrm{E}-01$ | $1.624 \mathrm{E}-02$ | $7.665 \mathrm{E}-01$ |
| 5 | $2.451 \mathrm{E}-03$ | $1.267 \mathrm{E}-01$ | $3.370 \mathrm{E}-02$ | $7.100 \mathrm{E}-01$ |
| 6 | $6.333 \mathrm{E}-04$ | $7.155 \mathrm{E}-02$ | $8.600 \mathrm{E}-04$ | $7.100 \mathrm{E}-01$ |
| 7 | $1.395 \mathrm{E}-04$ | $4.160 \mathrm{E}-02$ | $1.867 \mathrm{E}-04$ | $7.100 \mathrm{E}-01$ |
| 8 | $3.632 \mathrm{E}-05$ | $2.467 \mathrm{E}-02$ | $4.846 \mathrm{E}-05$ | $7.100 \mathrm{E}-01$ |
| 9 | $1.607 \mathrm{E}-05$ | $1.490 \mathrm{E}-02$ | $2.161 \mathrm{E}-05$ | $7.100 \mathrm{E}-01$ |

### 3.2 For $c_{1}=1, c_{2}=2, k_{11}=k_{12}=k_{21}=k_{22}=1$

Taking $w_{10}=c_{1}=1$, and $w_{20}=c_{2}=2$, and fixing the parameters $k_{11}=k_{12}=k_{21}=$ $k_{22}=1$, we obtain

$$
\begin{aligned}
\phi_{14}= & 1+\frac{3 c_{10}}{2}+\frac{11 c_{10}^{2}}{5}+\frac{2741 c_{10}^{3}}{2520}+\frac{7 c_{10} c_{20}}{40}+\frac{41 c_{10}^{2} c_{20}}{315}+\frac{65 c_{10} c_{20}^{2}}{1008}-\left(\frac{3 c_{10}}{2}+\frac{5 c_{10}^{2}}{2}\right. \\
& \left.+\frac{491 c_{10}^{3}}{360}+\frac{c_{10} c_{20}}{4}+\frac{73 c_{10}^{2} c_{20}}{360}+\frac{67 c_{10} c_{20}^{2}}{720}\right) x^{2}+\left(\frac{3 c_{10}^{2}}{10}+\frac{7 c_{10}^{3}}{24}+\frac{3 c_{10} c_{20}}{40}+\frac{c_{10}^{2} c_{20}}{12}\right. \\
& \left.+\frac{7 c_{10} c_{20}^{2}}{240}\right) x^{4}-\left(\frac{13 c_{10}^{3}}{840}+\frac{3 c_{10}^{2} c_{20}}{280}+\frac{c_{10} c_{20}^{2}}{1680}\right) x^{6} . \\
\phi_{24}= & 2+\frac{3 c_{20}}{2}+\frac{7 c_{10} c_{20}}{10}+\frac{893 c_{10}^{2} c_{20}}{2520}+\frac{67 c_{20}^{2}}{40}+\frac{769 c_{10} c_{20}^{2}}{2520}+\frac{3139 c_{20}^{3}}{5040}-\left(\frac{3 c_{20}}{2}+c_{10} c_{20}\right. \\
& \left.+\frac{191 c_{10}^{2} c_{20}}{360}+\frac{7 c_{20}^{2}}{4}+\frac{163 c_{10} c_{20}^{2}}{360}+\frac{487 c_{20}^{3}}{720}\right) x^{2}+\left(\frac{3 c_{10} c_{20}}{10}+\frac{23 c_{10}^{2} c_{20}}{120}+\frac{3 c_{20}^{2}}{40}\right. \\
& \left.+\frac{19 c_{10} c_{20}^{2}}{120}+\frac{13 c_{20}^{3}}{240}\right) x^{4}-\left(\frac{13 c_{10}^{2} c_{20}}{840}+\frac{3 c_{10} c_{20}^{2}}{280}+\frac{c_{20}^{3}}{1680}\right) x^{6} .
\end{aligned}
$$

Applying (2.18) and (2.19), we obtain optimal values $c_{10}=-0.689796, c_{20}=-0.708697$ and hence the HAM approximations to the solutions are obtained as

$$
\begin{aligned}
& \phi_{14}(x)=0.674423+0.271204 x^{2}+0.0454739 x^{4}+0.00889876 x^{6}, \\
& \phi_{24}(x)=1.67352+0.27178 x^{2}+0.0455586 x^{4}+0.00914259 x^{6}
\end{aligned}
$$

and by setting $c_{10}=c_{20}=-1$, the ADM approximations to the solutions are obtained as

$$
\begin{aligned}
& \psi_{14}(x)=0.592659+0.409722 x^{2}-0.0291667 x^{4}+0.0267857 x^{6} \\
& \psi_{24}(x)=1.59266+0.409722 x^{2}-0.0291667 x^{4}+0.0267857 x^{6} .
\end{aligned}
$$



Figure 3 Plots of HAM $\phi_{14}(x)$ and ADM $\psi_{14}(x)$ solutions


Figure 4 Plots of HAM $\phi_{24}(x)$ and ADM $\psi_{24}(x)$ solutions

Table 4 The HAM and ADM approximations to solutions

| $x$ | $\phi_{14}$ | $\psi_{14}$ | $\phi_{24}$ | $\psi_{24}$ |
| :--- | :---: | :---: | :---: | :---: |
| 0.0 | 0.674423143 | 0.592658730 | 1.673518521 | 1.592658730 |
| 0.1 | 0.677139742 | 0.596753063 | 1.676240889 | 1.596753063 |
| 0.2 | 0.685344640 | 0.609002667 | 1.684463213 | 1.609002667 |
| 0.3 | 0.699206350 | 0.629317007 | 1.698354439 | 1.629317007 |
| 0.4 | 0.719016401 | 0.657577333 | 1.718207120 | 1.657577333 |
| 0.5 | 0.745205361 | 0.693684896 | 1.744453865 | 1.693684896 |
| 0.6 | 0.778365260 | 0.737628444 | 1.777690385 | 1.737628444 |
| 0.7 | 0.819278422 | 0.789571015 | 1.818705108 | 1.789571015 |
| 0.8 | 0.868952703 | 0.849956000 | 1.868515392 | 1.849956000 |
| 0.9 | 0.928663139 | 0.919632507 | 1.928410306 | 1.919632507 |
| 1.0 | 1.000000000 | 1.000000000 | 2.000000000 | 2.000000000 |

Table 5 The absolute residual errors

| $x$ | $\operatorname{Res}_{14}(x)$ | res $_{14}(x)$ | $\operatorname{Res}_{24}(x)$ | $\operatorname{res}_{24}(x)$ |
| :--- | :---: | :---: | :---: | :---: |
| 0.0 | 0.043719198 | 1.163185862 | 0.047175755 | 1.163185862 |
| 0.1 | 0.042789989 | 1.143631002 | 0.046264512 | 1.143631002 |
| 0.2 | 0.040067370 | 1.086028837 | 0.043608077 | 1.086028837 |
| 0.3 | 0.035715976 | 0.993549036 | 0.039407953 | 0.993549036 |
| 0.4 | 0.029906016 | 0.871406768 | 0.033895791 | 0.871406768 |
| 0.5 | 0.022646550 | 0.726730135 | 0.027166674 | 0.726730135 |
| 0.6 | 0.013530025 | 0.568313445 | 0.018923646 | 0.568313445 |
| 0.7 | 0.001363158 | 0.406196710 | 0.008108600 | 0.406196710 |
| 0.8 | 0.016352278 | 0.250993596 | 0.007616937 | 0.250993596 |
| 0.9 | 0.044140746 | 0.112865431 | 0.032593096 | 0.112865431 |
| 1.0 | 0.089549318 | $1.17961 \mathrm{E}-16$ | 0.074158043 | $1.17961 \mathrm{E}-16$ |

Table 6 The maximum absolute residual errors

| $M$ | $R_{1 M}$ | $r_{1 M}$ | $R_{2 M}$ | $r_{2 M}$ |
| :--- | :---: | :---: | :---: | :---: |
| 2 | 1.0171100 | 2.00000 | 0.976732 | 2.000000 |
| 3 | 0.2902730 | 1.54514 | 0.142540 | 1.545140 |
| 4 | $4.371 \mathrm{E}-02$ | 1.16319 | $4.717 \mathrm{E}-02$ | 1.163190 |
| 5 | $2.824 \mathrm{E}-02$ | 0.96358 | $1.272 \mathrm{E}-02$ | 0.963584 |
| 6 | $4.308 \mathrm{E}-03$ | 0.79717 | $4.546 \mathrm{E}-03$ | 0.797179 |
| 7 | $1.188 \mathrm{E}-03$ | 0.69863 | $1.263 \mathrm{E}-03$ | 0.698631 |
| 8 | $1.288 \mathrm{E}-04$ | 0.55557 | $1.367 \mathrm{E}-04$ | 0.555577 |
| 9 | $1.721 \mathrm{E}-05$ | 0.50333 | $1.795 \mathrm{E}-05$ | 0.503336 |

Remark 3.1. One can note that in the Tables 6, we observe that the HAM (present method) gives stable and convergent solution.

## 4 Conclusion

We have examined a system of coupled Lane-Emden BVPs that models many physical and chemical phenomena such as catalytic diffusion reactions. We employed the HAM combined with the Green's function strategy [1]. Our approach enhances the computational efficiency while overcoming the difficulty of the singular behavior at the origin $x=0$. The HAM was used systematically in a straightforward manner. The obtained results were supported by proper figures to show the power of the method and to show the enhancements over exiting techniques such as the ADM [26]

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